

Algorithms for Information Security  
and Privacy 2017

# 10.

## Recap: Point Addition on Elliptic Curve

Suppose that  $P = (x_1, y_1)$ ,  $Q = (x_2, y_2)$

$P + Q = (x_3, y_3)$  where,

$$m = \frac{y_2 - y_1}{x_2 - x_1} = (y_2 - y_1) \cdot (x_2 - x_1)^{-1}$$

Computation time  
for field inversion

$$O(\log^3 p)$$

$$c = y_1 - m \cdot x_1$$

Bottleneck of Point Addition,

$$x_3 = m^2 - x_1 - x_2$$

$$y_3 = -m \cdot x_3 - c$$

This class: Reduce the computation for field inversion

$$M = y_2 - y_1 \quad Z_3 = x_2 - x_1$$

$$m = M \cdot Z_3^{-1}$$

$$c = y_1 - M \cdot Z_3^{-1} \cdot x_1$$

$$x_3 = m^2 - x_1 - x_2 = M^2 \cdot Z_3^{-2} - x_1 - x_2$$

$$= Z_3^{-2} \left[ \underbrace{M^2 - x_1 \cdot Z_3^2 - x_2 \cdot Z_3^2}_{X_3} \right]$$

$$= X_3 \cdot Z_3^{-2}$$

$$y_3 = -m x_3 - c$$

$$= -M \cdot Z_3^{-1} \cdot X_3 \cdot Z_3^{-2} - y_1 + M \cdot Z_3^{-1} \cdot x_1$$

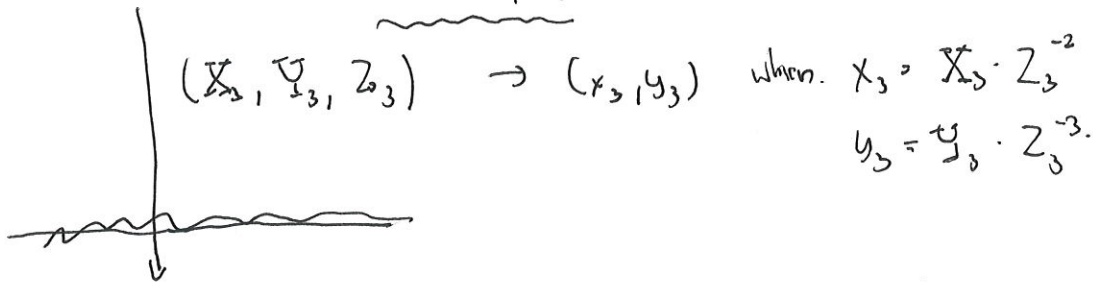
$$= Z_3^{-3} \left[ \underbrace{-M \cdot X_3 - y_1 \cdot Z_3^3 + M \cdot x_1 \cdot Z_3^2}_{Y_3} \right]$$

$$Y_3$$

$$= Y_3 \cdot Z_3^{-3}$$

$$(x_2, y_2) + (x_2, y_2) = (x_3, y_3) \rightarrow \text{before}$$

$$(x_2, y_2) + (x_2, y_2) = (\underline{X_3}, \underline{Y_3}, Z_3) \rightarrow \text{point in Jacobian Coordinate.}$$



$$(\underline{X_3}, \underline{Y_3}, Z_3) \rightarrow (x_3, y_3) \text{ when. } x_3 = X_3 \cdot Z_3^{-2}$$

$$y_3 = Y_3 \cdot Z_3^{-3}.$$

$$\text{Complexity} = O(\log^2)$$

⚡ Multiplication is the bottleneck operation.

P+Q+R

$$(\underline{X_3}, \underline{Y_3}, Z_3) + (x_4, y_4) = (x_4, y_4) + (\underline{X_3}, \underline{Y_3}, Z_3) = (x_5, y_5)$$

$$m = \frac{y_3 - y_4}{x_3 - x_4} = \frac{(Y_3 \cdot Z_3^{-3} - y_4) \cdot (X_3 \cdot Z_3^{-2} - x_4)^{-1}}{Z_3 \cdot (Y_3 - y_4 \cdot Z_3^3) \cdot Z_3^{-1} (X_3 \cdot Z_3 - x_4 Z_3^2)^{-1}}$$

$$= \frac{M}{Z_5'} \cdot Z_5'^{-1}$$

$$= M \cdot Z_5'^{-2}$$

$$c = y_4 - m x_4 = y_4 - M \cdot (Z_5')^{-1} \cdot x_4$$

$$x_5 = m^2 - x_4 - x_3$$

$$= (M \cdot (Z_5')^{-1})^2 - x_4 - X_3 \cdot Z_3^{-2}$$

$$= M^2 \cdot \underline{Z_5'^{-2}} - x_4 - \underline{X_3 \cdot Z_3^{-2}}$$

$$= Z_5'^{-2} \cdot Z_3^{+2} \left[ \underline{M^2 \cdot Z_3^2 - x_4 Z_3^2 \cdot Z_5'^2 - X_3 \cdot Z_5'^2} \right]$$

$$\quad \quad \quad \underline{X_5}$$

$$= \frac{(Z_5' \cdot Z_3)^{-2}}{Z_5} \cdot X_5$$

$$x_5 = Z_5^{-2} \cdot X_5$$

(2.2.2)

$$y_5 = -m \cdot x_5 - c$$

$$= -M \cdot Z_5^{1-1} \cdot Z_3^{-2} X_3 - y_4 + M \cdot Z_5^{1-1} \cdot x_4$$

$$= \frac{Z_5^{-2} \cdot Z_3^{1-1} \cdot Z_3^{-1}}{Z_3^{-1}} \left[ -M \cdot Z_3 \cdot X_3 - y_4 \cdot Z_5^2 \cdot Z_3^{1-1} \cdot Z_3 + M \cdot Z_3^2 \cdot Z_3 \cdot x_4 \right]$$

$$= Z_5^{-3} \cdot Y_3$$

Conclusion

$$(X_3, Y_3, Z_3) + (x_4, y_4) = (X_5, Y_5, Z_5)$$

$$\text{when } M = Y_3 - y_4 \cdot Z_3^3$$

$$Z_5' = X_3 \cdot Z_3 - x_4 \cdot Z_3^3$$

$$Z_5 = Z_5' \cdot Z_3$$

$$X_5 = M^2 \cdot Z_3^2 - x_4 \cdot Z_3^2 \cdot Z_5^2 - X_3 \cdot Z_5^2$$

$$Y_5 = -M \cdot Z_3 \cdot X_5 - y_4 \cdot Z_5^2 \cdot Z_5' \cdot Z_3 + M \cdot Z_5^2 \cdot Z_3 \cdot x_4$$

Bottleneck is field multiplication  $O(\log^2 p)!!$ .

Before  $(x_1, y_1) + (x_2, y_2) + (x_4, y_4)$   
 ↑ one point inversion      ↑ one point inversion

with Jacobian coordinate

$$(x_1, y_1) + (x_2, y_2) + (x_4, y_4)$$

$$\xrightarrow{\text{no point inversion}} (X_3, Y_3, Z_3) + (x_4, y_4)$$

$$\xrightarrow{\text{no point inversion}} (X_5, Y_5, Z_5)$$

↓ one point inversion

$$(x_5, y_5) = (X_5 \cdot Z_5^{-2}, Y_5 \cdot Z_5^{-3})$$

2 point inversions

↓

1 point inversion

## Recap: Scalar Multiplication

$$aP = \underbrace{P + P + \dots + P}_{a \text{ times}}$$

$a$  is as big as  $2^f$

$$57 = 32 + 16 + 8 + 1$$

$$= 2^5 + 2^4 + 2^3 + 2^0$$

$$57P = \underbrace{2^5 P} + \underbrace{2^4 P} + \underbrace{2^3 P} + \underbrace{2^0 P}$$

Calculate each point separately and add them together

Faster way:  $2^0 P \rightarrow 2^1 P \rightarrow 2^2 P \rightarrow 2^3 P \rightarrow 2^4 P \rightarrow 2^5 P$   $O(\lg p)$  additions  
Add together to have  $57P$   $O(\lg p)$  additions.

Without Jacobian  
Coordinate

$O(\lg^2 p)$  per addition  $\rightarrow O(\lg^4 p)$  per scalar multiplication

With Jacobian  
Coordinate

$O(\lg^2 p)$  per addition  $\rightarrow O(\lg^3 p)$  per scalar multiplication  
+  $O(\lg^3 p)$  for point inversion

converting Jacobian  
to normal.

## Double-Base Number Representation

$$57 = 2^5 + 2^4 + 2^3 + 2^0$$

binary representation

$$57 = 2 \cdot 3^2 + 3^1 + 3^0$$

ternary representation

[not that better in practice  
still  $O(\lg^3 p)$  per scalar multiplication]

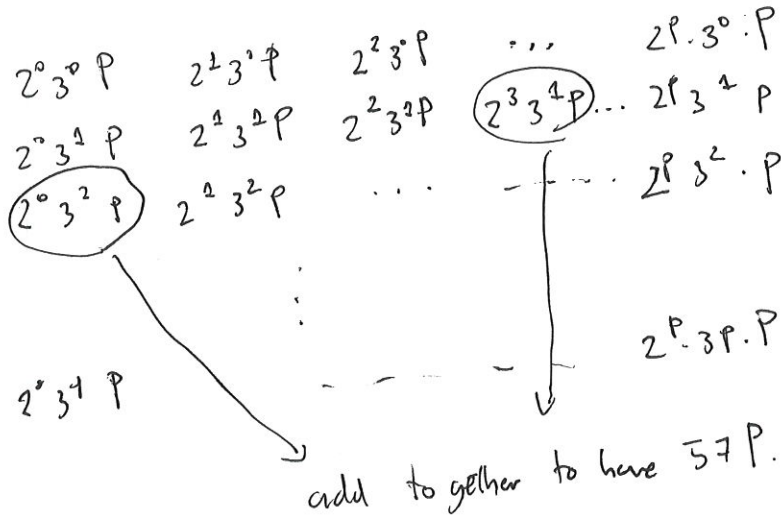
merge

$$57 = \underline{2^3 \cdot 3^1} + 3^2 = 48 + 9$$

Double-Base Number Representation.

Situation:  $P$  (our own private key) is fixed, and  $a$  (value obtained from partner) is different on each Scalar Point Multiplication.

Pre-compute



How to find Double-based number representation?

- we want to find a representation with smallest # terms  $\rightarrow$  smallest # additions.
- greedy algorithm.
  - o Suppose that we want to calculate  $a \cdot P$

1:  $Q \leftarrow 0$

2: Find the largest  $2^i 3^j$  that is no larger than  $a$ .

3:  $Q \leftarrow Q + 2^i 3^j P$

4:  $a \leftarrow a - 2^i \cdot 3^j$

5: If  $a = 0$ , then terminates

Otherwise, go to Step 2.

Theorem. [Dimitrov, Lambert, Mishra, Maths of Computation '08]

# terms obtained from greedy algorithm  $= O(\lg p / \lg \lg p)$   
 $=$  # additions.

# Computation time using Double-based number system

$= O(\lg^3 p / \lg \lg p)$

16 when  $p \approx 2^{256}$

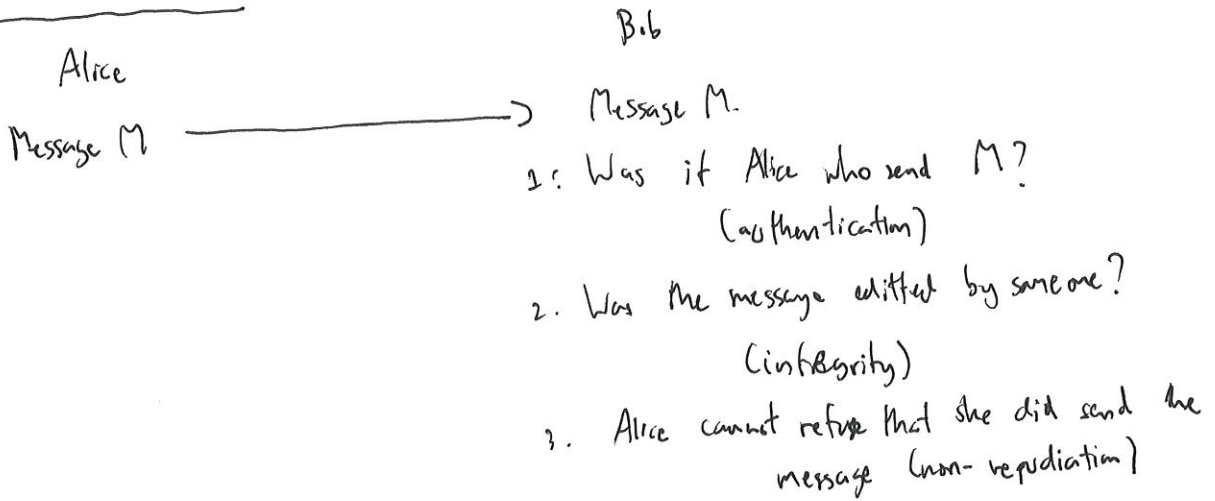
Question: Is it possible to have something better than  $O(\lg p / \lg \lg p)$  terms?

Theorem [Saranurak, Suppakitsorn, unpublished]

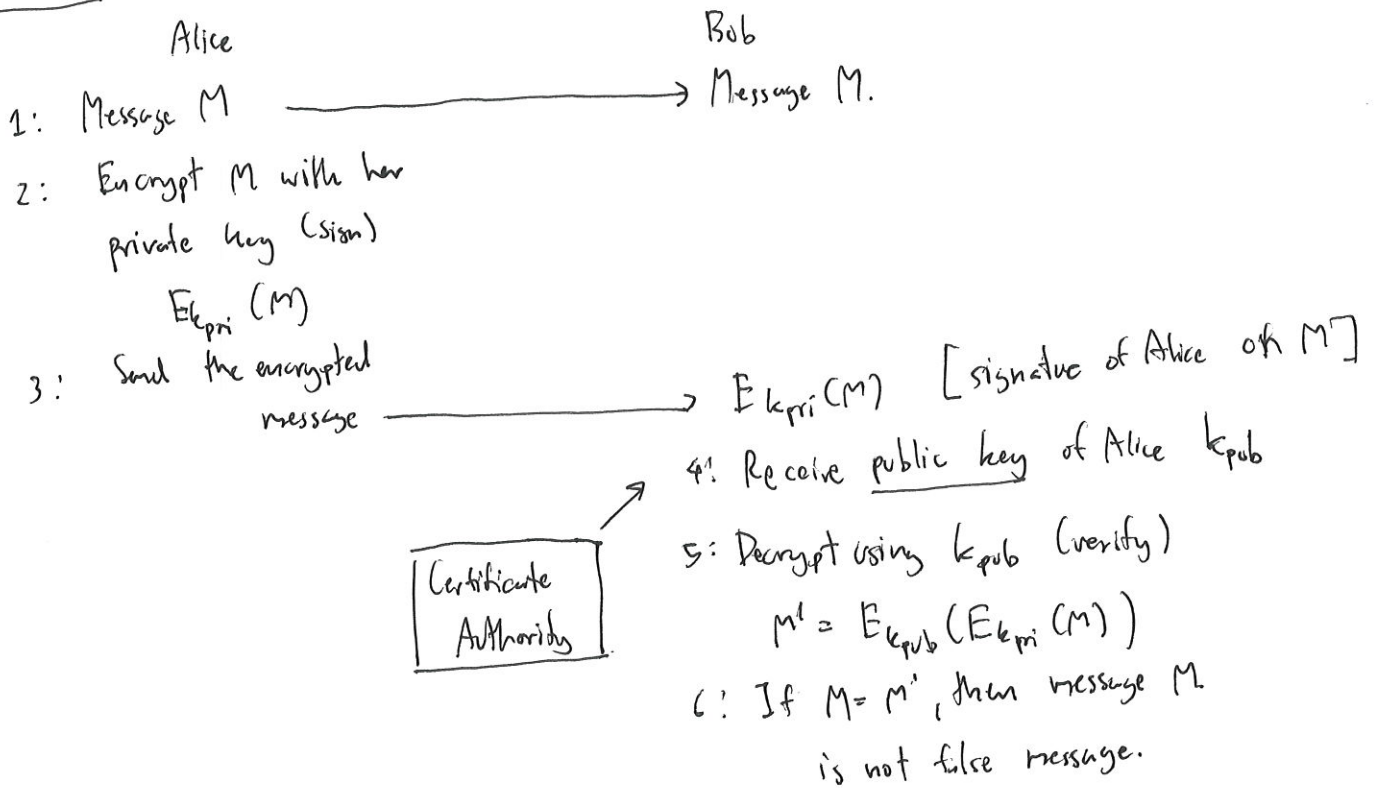
No representation has #terms =  $o(\lg p / \lg \lg p)$ .

---

### Elliptic Curve Digital Signature



### Rough Idea





# El Gamal's Digital Signature [ElGamal 1985]

Alice  
 Private key  $a \in \mathbb{Z}_p$   
 Public key  $A, B (= a \cdot A)$

Bob  
 Public Key  $A, B$

$M \in \mathbb{Z}_p$  [Random number  $k$ ]

Signing  $R = k \cdot A = (x_R, y_R)$   
 $s = (m - ax_R) \cdot k^{-1}$

$(R, s) \longrightarrow (R, s)$

Calculate  $x_R B + s R$  verifying  
 Verify if the value  $= m \cdot A$

When every thing is alright.

$$\begin{aligned} x_R B + s \cdot R &= x_R \cdot aA + (m - ax_R) k^{-1} \cdot k \cdot A \\ &= x_R \cdot aA + mA - ax_R A \\ &= mA \end{aligned}$$

If I am attacker... (I want to tell Bob that I am Alice)

• I can choose  $k$  freely and calculate  $R = k \cdot A = (x_R, y_R)$

• But, I need  $a$  to calculate  $s$ .

[If I do not have correct  $a$ , 2 terms cannot be cancelled]

• I can learn  $a$  from  $A, B \rightarrow$  Discrete Logarithm problem.

• I can learn from  $R$  and  $s$  sent by Alice.

$$s = (m - ax_R) k^{-1}$$

$\uparrow$  known     $\uparrow$  known     $\uparrow$  known     $\uparrow$  unknown

• To know  $k$ , we have to solve discrete logarithm when the inputs are  $R$  and  $A$ .  
 $(= kA)$